






# Dalia Marcela Rojas Castro

## Ph.D. in Computer Sciences and Applications

Working in the Industry after a PhD path



11th June 2021

Place	 <p>University of Montpellier LIRMM Lab</p>	 <p>Nanyang Technological University Robotics Research Lab (RRC)</p>	 <p>La Rochelle University Informatique, Image et Interaction (L3i)</p>	 <p>La Rochelle University Informatique, Image et Interaction (L3i)</p>	 <p>Kyoto University HRI Laboratory</p>
Position	Engineer workplacement	Research engineer workplacement	Master Research workplacement & Doctoral thesis	Postdoctoral researcher	Postdoctoral research visitor
Supervisors	Professor Lionel Lapierre Professor Philippe Fraise	Professor Seet Gim Lee, Gerald Dr. Viatcheslav Lastrebov	Professor Michel Ménard Professor Arnaud Revel	Professor Michel Ménard Professor Arnaud Revel Professor Yacine Ghamri-Doudane Assistant professor Cyril Fauchier	Professor Takayuki Kanda
Project	Human-Robot Interaction with NAO humanoid robot	Implementation of Doppler Techniques for Detection and Characterization of Negative Obstacles by high speed mobile platforms (HSMP)	The RHIZOME Architecture: A Hybrid Neurobehavioral Control Architecture for Autonomous Vision-based Indoor Robot Navigation.	<ul style="list-style-type: none"> <li><b>Towards social robots at the services of the elderly</b></li> <li><b>IoT-based management of major crisis</b></li> </ul>	<b>Intention recognition of aggressive pedestrians in public spaces</b>
	May 2011	March. 2012	January 2017	March 2019	July 2019



University of Montpellier  
LIRMM Lab



Nanyang Technological University  
Robotics Research Lab (RRC)



La Rochelle University  
Informatique, Image et Interaction (L3i)



Kyoto University  
HRI Laboratory

Place

Position

Supervisors

Project

Engineer workplacement	Research engineer workplacement	Master Research workplacement & Doctoral thesis	Postdoctoral researcher	Postdoctoral research visitor
Professor Lionel Lapierre Professor Philippe Fraise	Professor Seet Gim Lee, Gerald Dr. Viatcheslav Lastrebov	Professor Michel Ménard Professor Arnaud Revel	Professor Michel Ménard Professor Arnaud Revel Professor Yacine Ghamri-Doudane Assistant professor Cyril Fauchier	Professor Takayuki Kanda
Human-Robot Interaction with NAO humanoid robot	Implementation of Doppler Techniques for Detection and Characterization of Negative Obstacles by high speed mobile platforms (HSMP)	The RHIZOME Architecture: A Hybrid Neurobehavioral Control Architecture for Autonomous Vision-based Indoor Robot Navigation.	<ul style="list-style-type: none"> <li><b>Towards social robots at the services of the elderly</b></li> <li><b>IoT-based management of major crisis</b></li> </ul>	<b>Intention recognition of aggressive pedestrians in public spaces</b>

May 2011

March. 2012

January 2017

March 2019

July 2019

# From Academia to Industry



Place



La Rochelle University

Kyoto University

Informatique, Image et Interaction (L3i)

HRI Laboratory

Position

Master Research  
workplacement & Doctoral  
thesis

Postdoctoral researcher



Ontology Modelling Technical  
Leader & Scrum Master

Project

Airbus - DDMS

January 2017

July 2019

February 2020

# Job hunting




Highlight the skills acquired during the PhD and Postdocs. Specially the ones that are not technical.





Once in a company, the learning and adaptation curve grows exponentially thanks to the experiences and skills we have acquired in Academia.

	February 2020	April 2020	July 2020	December 2020
Situation	Ontology Modelling Expert ( new comer)	« Chomage Partiel »	Ontology Modelling Expert	Ontology Modelling Technical Leader & Scrum Master
Team Members	4 members interacting with 5 teams	Home alone 	3 members interacting with 3 teams	6 members interacting with Several teams  3 research European Labs

THANK YOU FOR YOUR  
ATTENTION

